Quantifying Uncertainty In Computational Knowledge Engineering Rapidly

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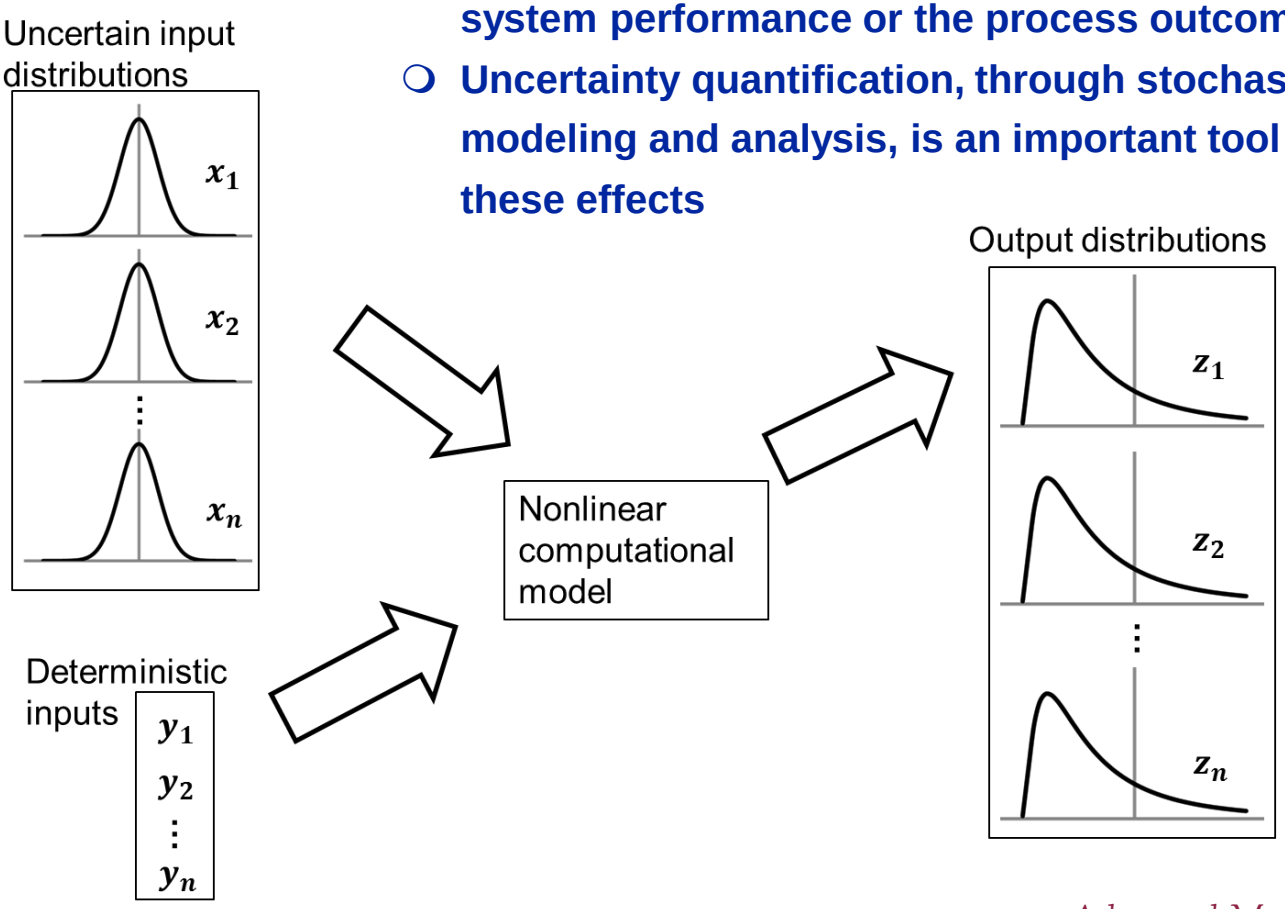
Motivation for Uncertainty Quantification

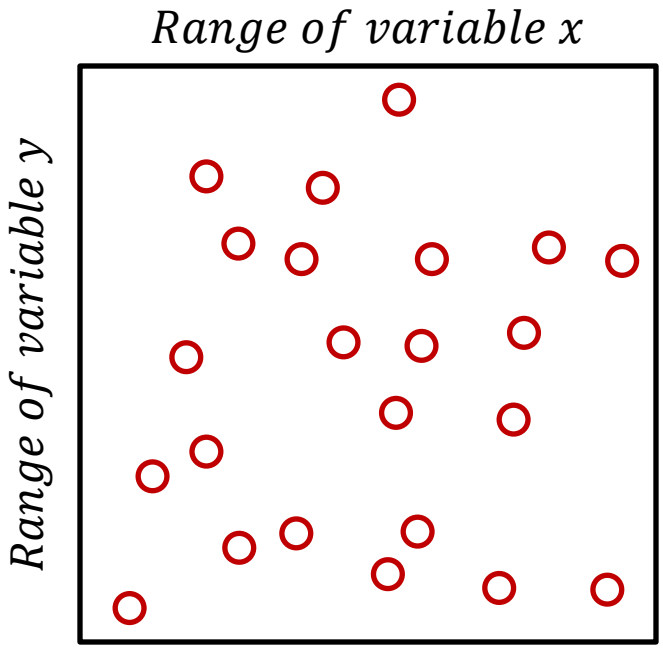
- **Multiphase systems operate in an environment of uncertainty**
  - **This uncertainty exists in both the parameters governing the system and in the process behavior**
  - **The interactive effect of uncertainty leads to variability in the system performance or the process outcomes**
  - **Uncertainty quantification, through stochastic computational modeling and analysis, is an important tool for investigating these effects**



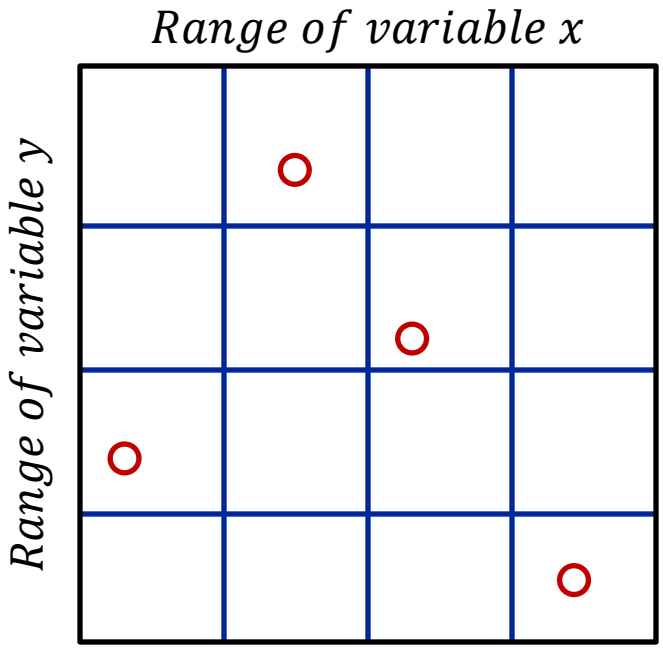
Current Methodologies

- Conventional methods seek to mimic physical processes
  - Monte Carlo methods randomly select inputs from the input distributions
  - Stratified methods (such as the Latin Hypercube method) seek to reduce the number of experiments, but still generate a representative sample
  - Both methods are VERY computationally intensive

Monte Carlo Sampling



Latin Hypercube Sampling

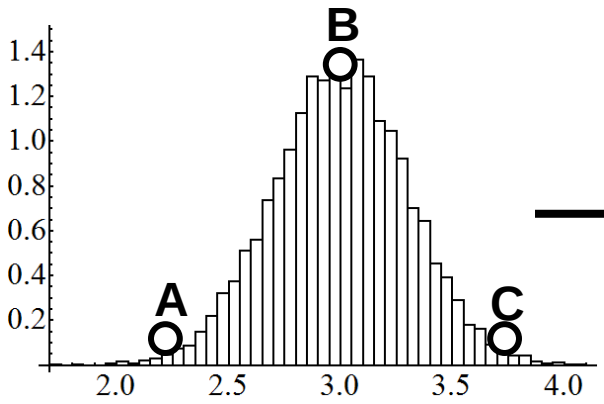


Overview of QUICKER

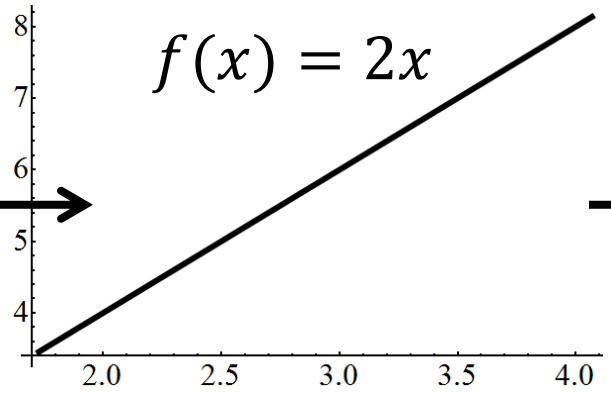
- QUICKER (Quantifying Uncertainty In Computational Knowledge Engineering Rapidly)
  - QUICKER is a new methodology that is intended to be used instead of conventional sampling methods such as Lathin Hypercube Sampling, Monte Carlo Sampling, Quasi-Monte Carlo Sampling, etc.
  - Since sampling, effectively running computational simulations, is the most time consuming aspect of Uncertainty Quantification, the significant reduction in computational costs from using QUICKER make Uncertainty Quantification far more affordable
- QUICKER is orders of magnitude faster than conventional sampling
  - Through the use of QUICKER, it is typical to see computational time reductions in excess of 99% of the time required for conventional methods
- QUICKER does not sacrifice accuracy
  - Typical RMS differences between QUICKER and conventional methodologies are less than 8%
- QUICKER is noninvasive and transparent
  - QUICKER can be implemented without modifying the simulation source code
  - The QUICKER methodology does not require esoteric math or complicated algorithms

Identifying key points to sample

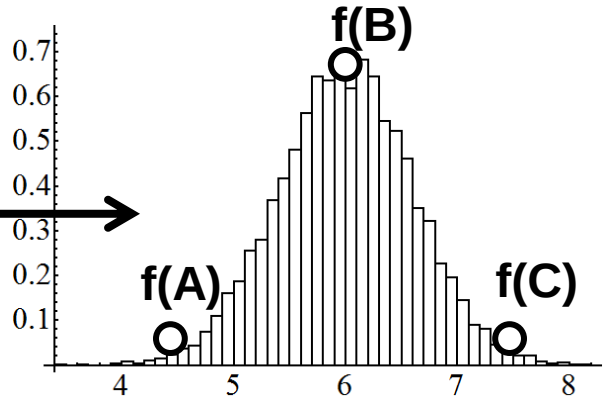
Gaussian input distribution

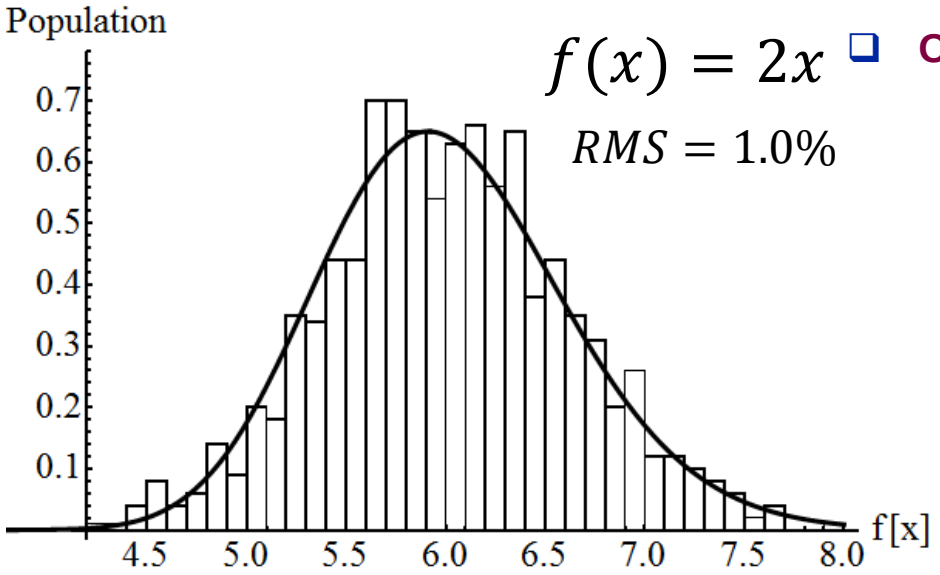


Monotonic system



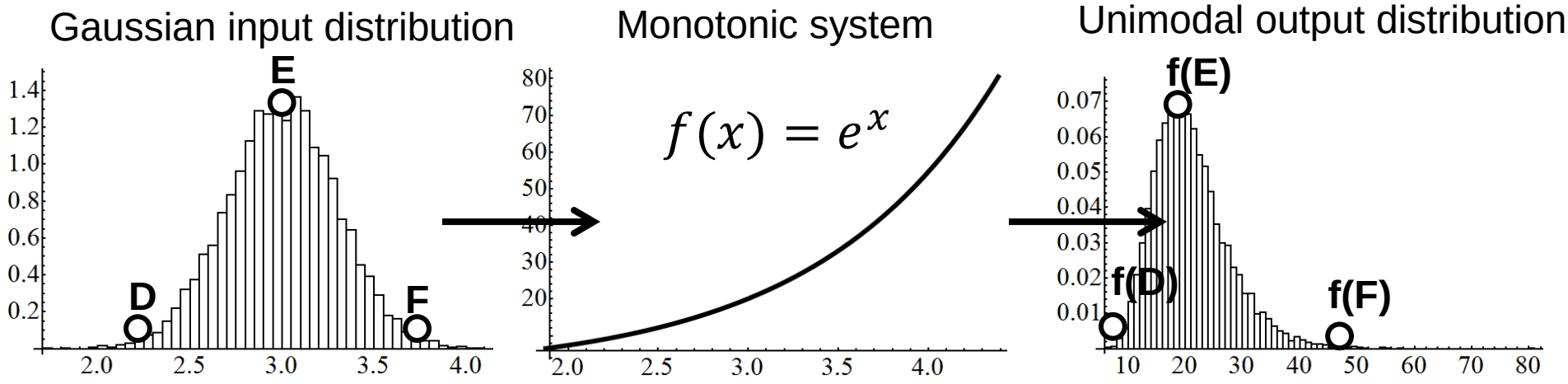
Unimodal output distribution

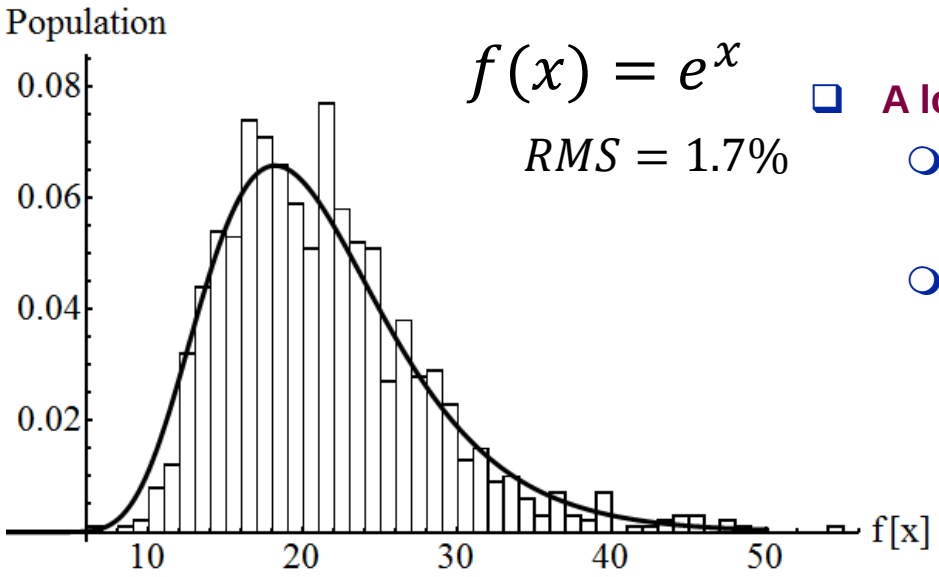




- **Only a small number of key points are necessary**
  - **For a monotonic system with a Gaussian input, it is necessary to select only a few input points in order to completely define the output distribution**
  - **These points are chosen at the mean and equal standard deviations**

Using a lognormal output distribution

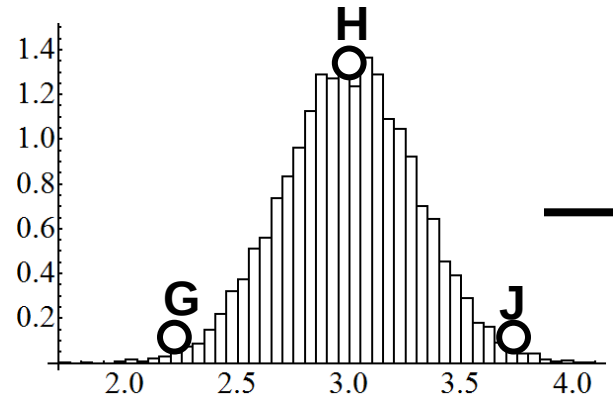




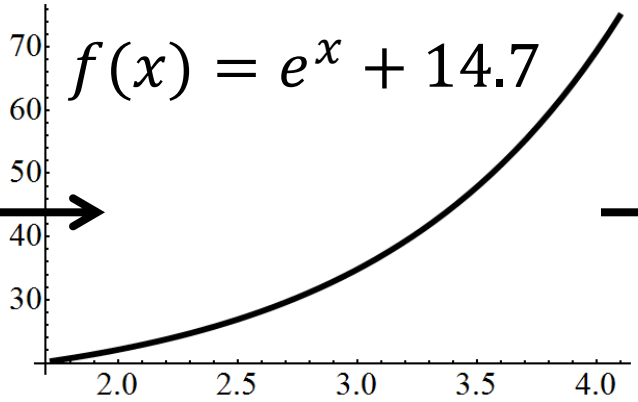
- **A lognormal distribution is versatile**
  - **A lognormal distribution can be used to represent symmetric or positive skewness**
  - **Therefore, lognormal distributions will be used in QUICKER**

Accounting for constant offset

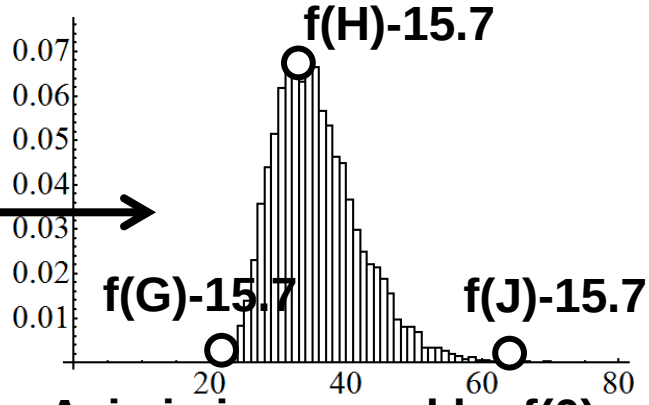
Gaussian input distribution



Offset monotonic system

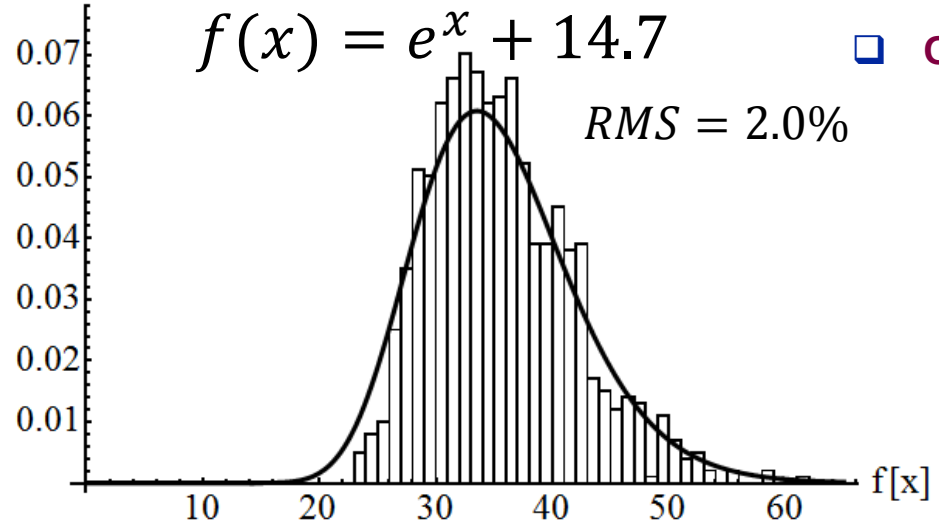


Unimodal output distribution



Axis is increased by f(0), 15.7 in this instance

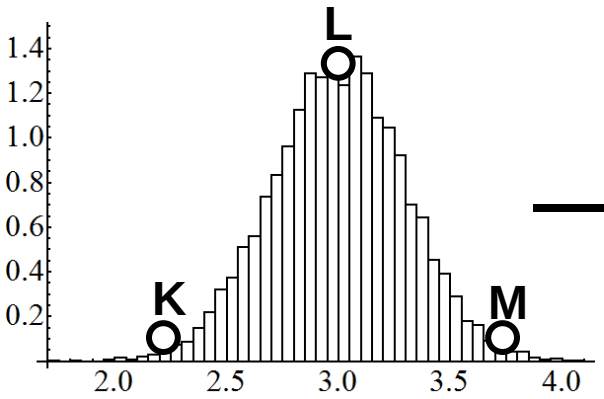
Population



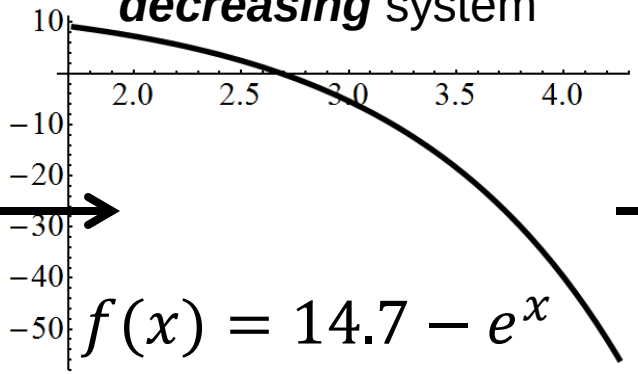
- **Certain systems have a constant offset**
  - **The lognormal distribution assumes that $f(x = 0) = 0$, and therefore it is necessary to account for any systematic offsets by taking an additional data point**

Accounting for negative skewness

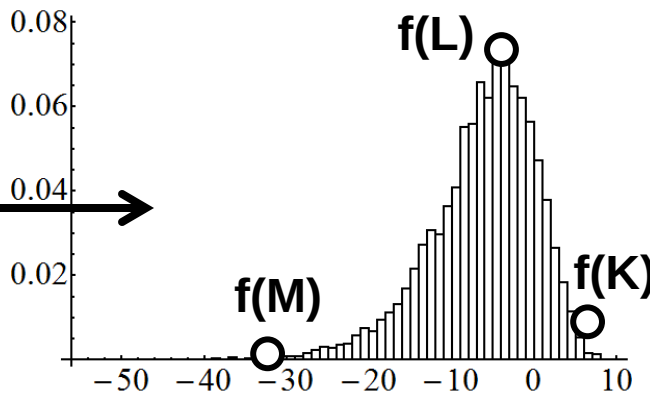
Gaussian input distribution



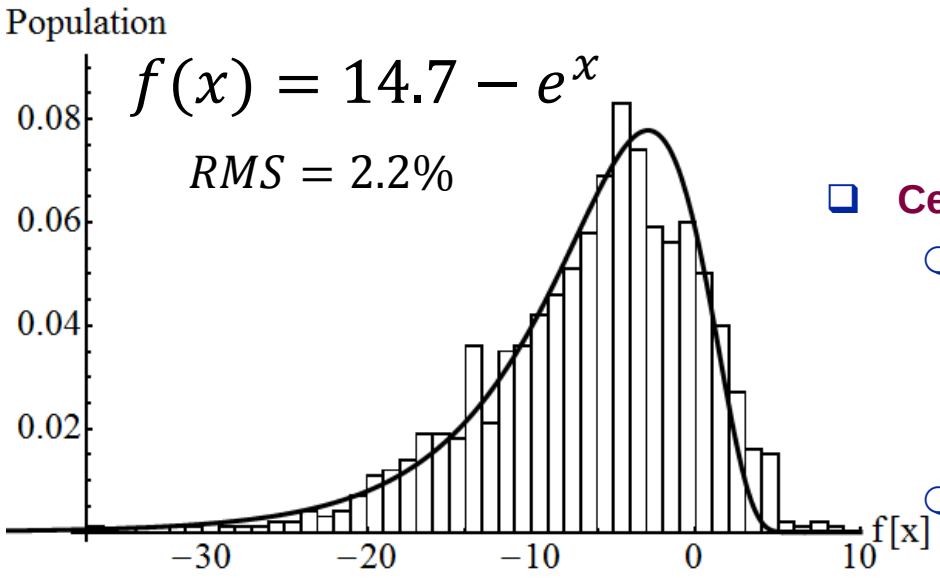
Monotonically ***decreasing*** system



Unimodal output distribution



Axis is flipped about the max result, f(K) in this instance

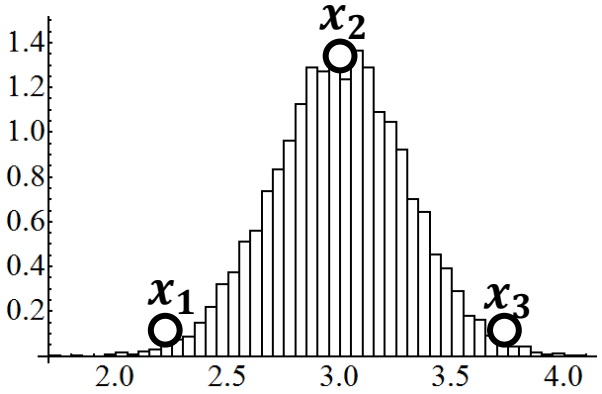


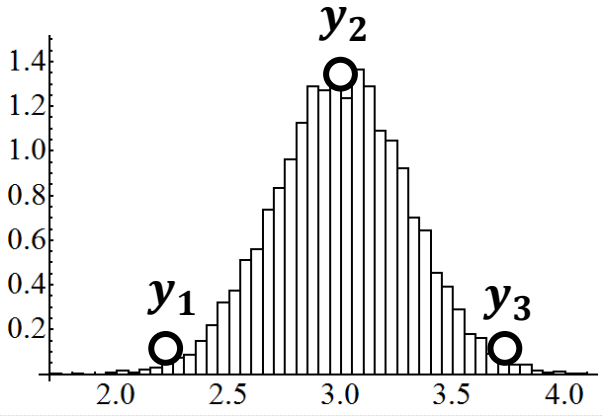
- **Certain outputs have a negative skewness**
  - **The lognormal distribution has a positive skewness, and in order to account for this, the plot needs to be "flipped" about the maximum point**
  - **Note that the function reverses the relative magnitude of the inputs**

Sampling within QUICKER

For a system with two input distributions, three points are selected on each input distribution

Input distr.	$\mu - N\sigma$	μ	$\mu + N\sigma$
x	x_1	x_2	x_3
y	y_1	y_2	y_3





The minimums and means are simulated, and then an orthogonal array is used to combine the extremes

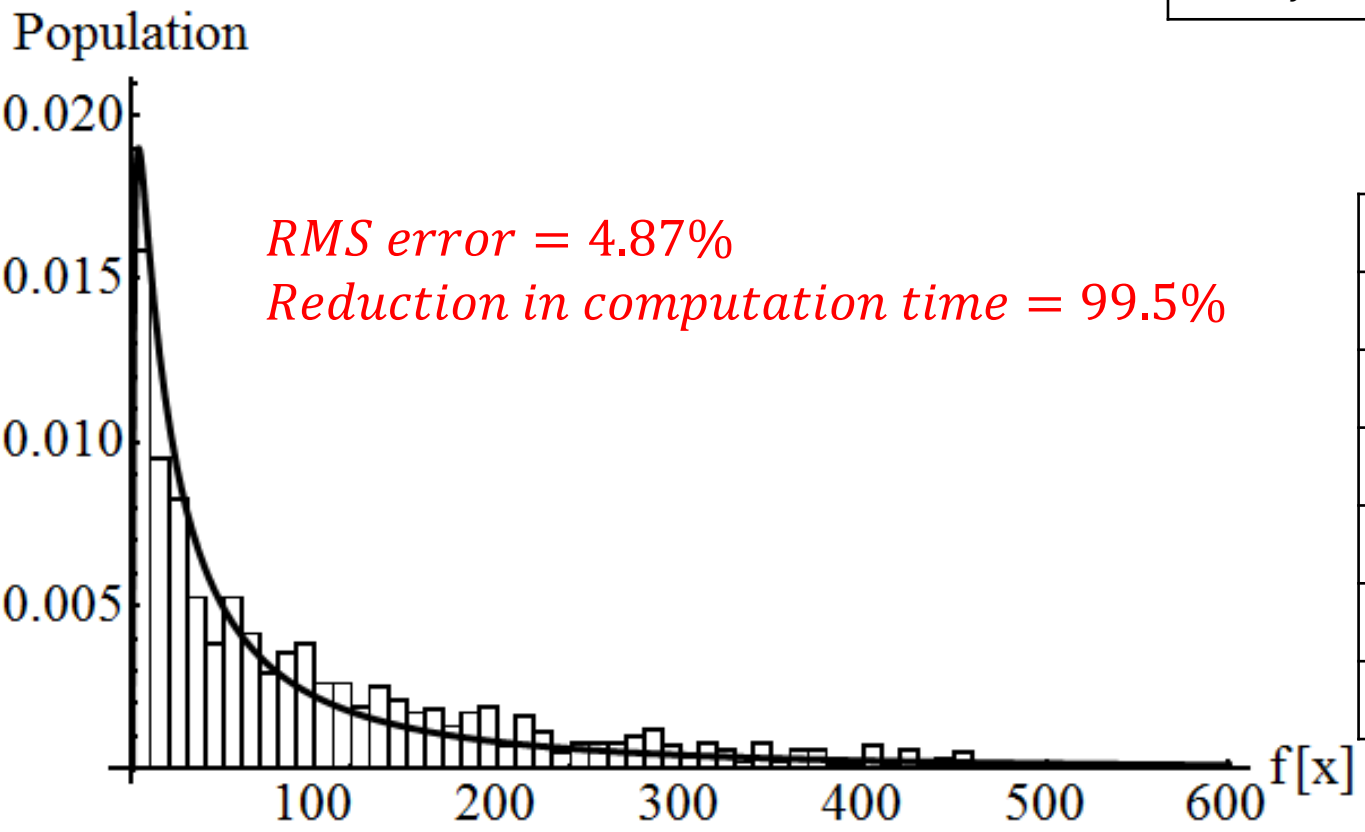
Simul. #	x	y
min	min	min
1	x_2	y_2
2	x_1	y_1
3	x_1	y_3
4	x_3	y_1
5	x_3	y_3

A specific example of QUICKER

The Rosenbrock function is a typical test case for optimization routines

$$f(x,y) = 100 * (y - x^2)^2 + (1 - x)^2$$
$$\mu_x = 0,\ \sigma_x = 0.67$$
$$\mu_y = 1,\ \sigma_y = 0.67$$

Input distr.	$\mu - 3\sigma$	μ	$\mu + 3\sigma$
x	-2.01	0	2.01
y	-1.01	1	3.01



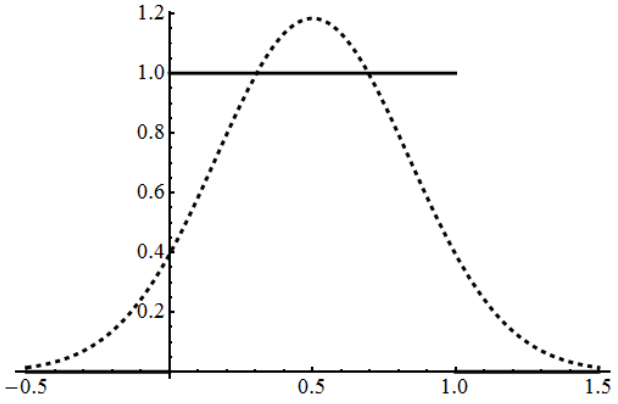
RMS error $= 4.87\%$
Reduction in computation time $= 99.5\%$

Simul. #	x	y
min	1	1
1	0	1
2	-2.01	-1.01
3	-2.01	3.01
4	2.01	-1.01
5	2.01	3.01

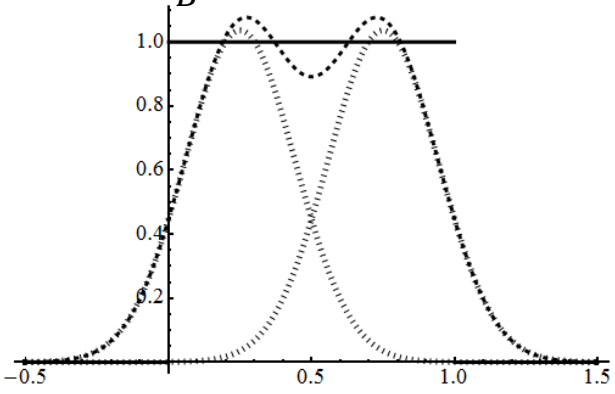
Composite representation of uniform

$U = length\ of\ uniform\ range$
$U_0 = lower\ bound$

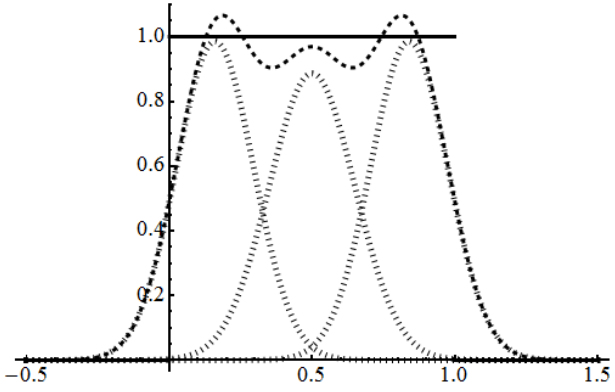
$\mu = 0.5U + U_0$
$\sigma = 0.337U$



$\mu_A = 0.25U + U_0$
$\mu_B = 0.75U + U_0$
$\sigma_A = 0.1925U$
$\sigma_B = 0.1925U$



$\mu_A = 0.16U + U_0$
$\mu_B = 0.5U + U_0$
$\mu_C = 0.84U + U_0$
$\sigma_A = 0.135U$
$\sigma_B = 0.15U$
$\sigma_C = 0.135U$



- **Epistemic uncertainty is typically represented as a uniform distribution**
  - **A combination of Gaussian distributions can be used to represent a uniform distribution**
  - **Note that the Gaussian distribution is scaled depending on the uniform distribution**

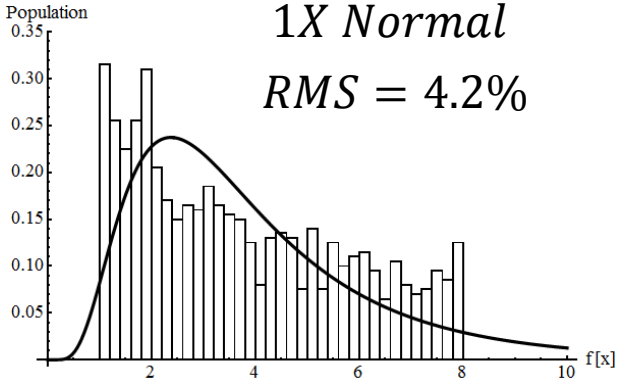
Results of composite uniform

$Uniform\ input\ distribution: [1, 2]$ $f(x) = x^3 + 1$

$Time\ reduction = 99.7\%$

$1X\ Normal$

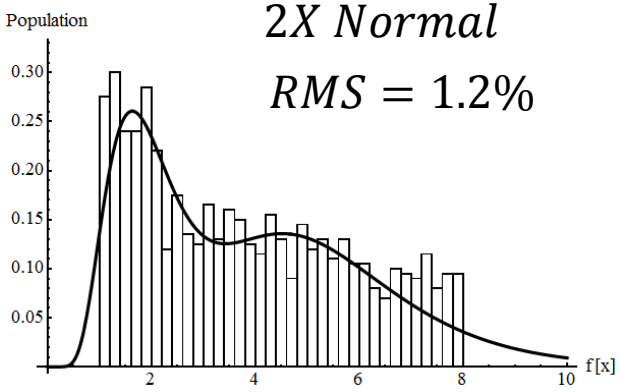
$RMS = 4.2\%$



$Time\ reduction = 99.4\%$

$2X\ Normal$

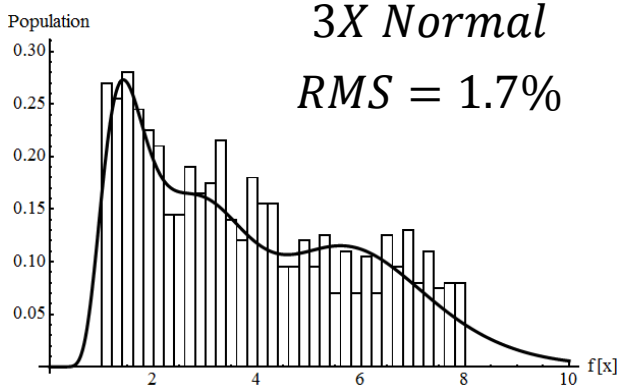
$RMS = 1.2\%$



$Time\ reduction = 99.1\%$

$3X\ Normal$

$RMS = 1.7\%$

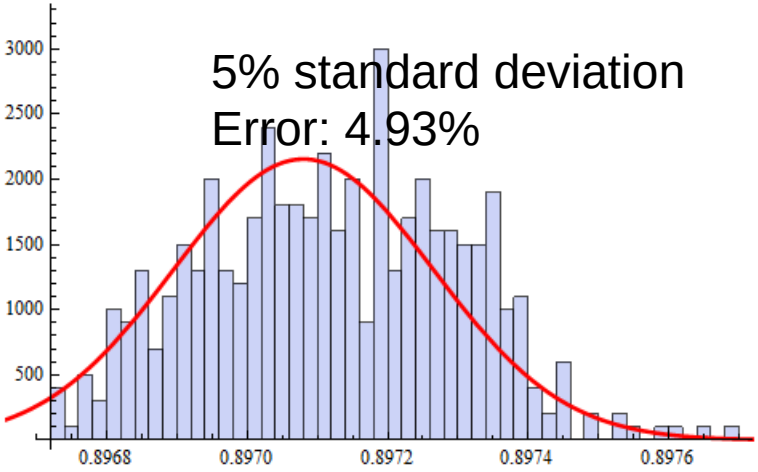


- To a point, composite distributions can provide a more accurate prediction
  - Functions of only one variable are typically the hardest to represent with uniform composite distirbutions
  - Note that the improvement from 2X to 3X composite distribution is negligible

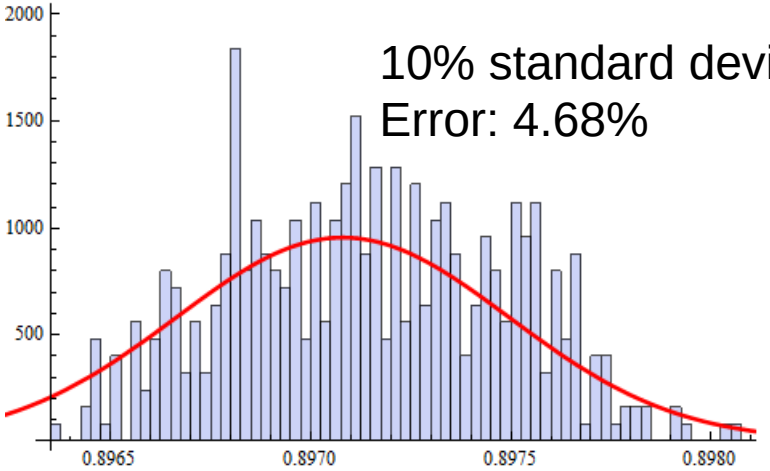
3dCfb MFIX scenario with 1X uniform

LHS computation time: 125.56 hours
QUICKER computation time: 4.52 hours
Computational time savings of *96.4%*

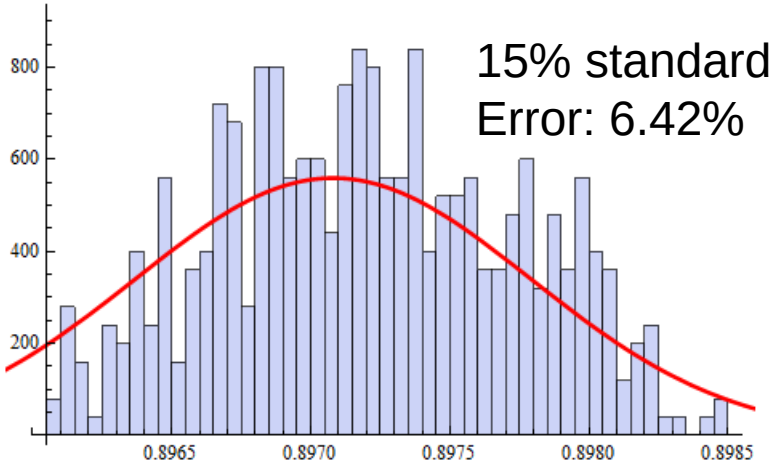
Measuring porosity at a specified location



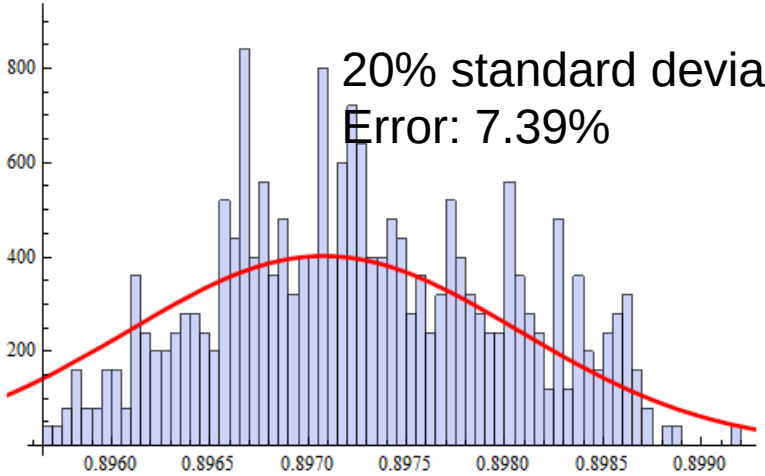
5% standard deviation
Error: 4.93%



10% standard deviation
Error: 4.68%



15% standard deviation
Error: 6.42%

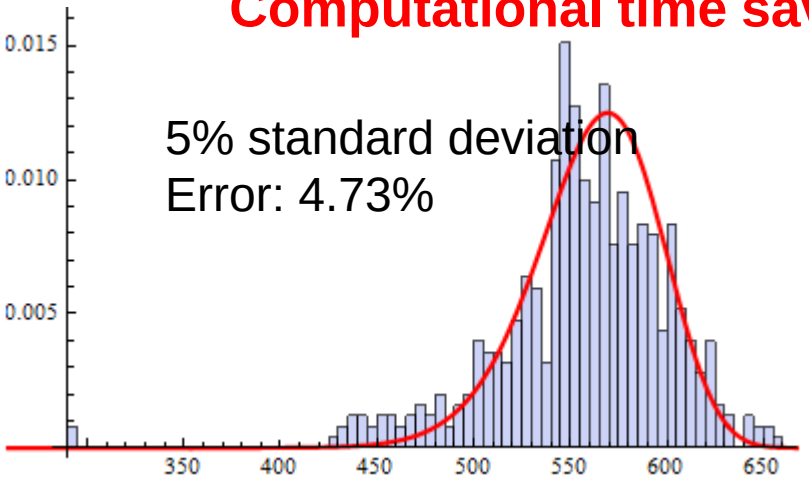


20% standard deviation
Error: 7.39%

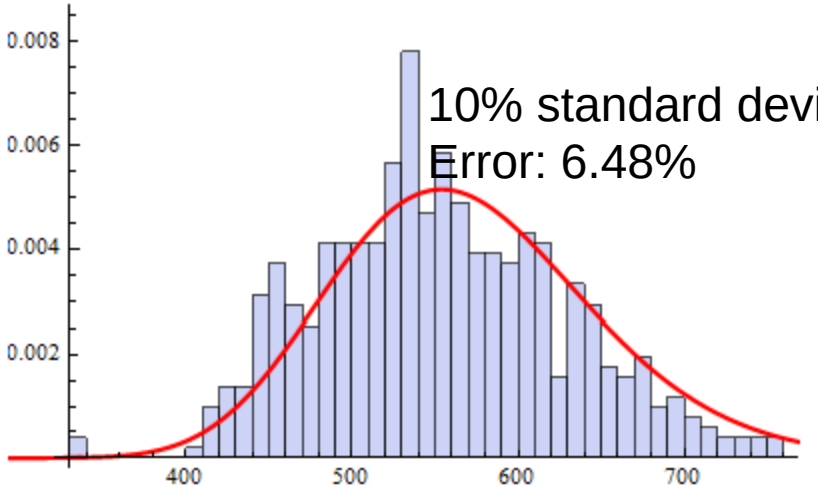
Ahmadi MFIX scenario with 1X uniform

LHS computation time: 4.58 hours
QUICKER computation time: 0.10 hours
Computational time savings of 97.8%

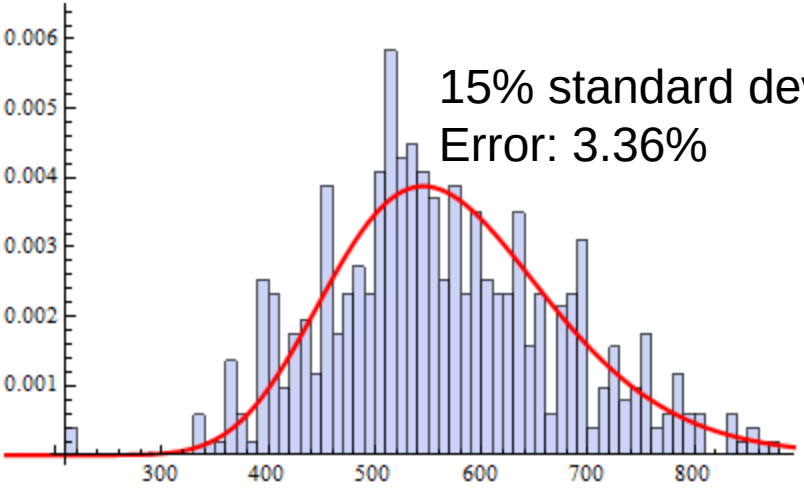
Measuring solid velocity at a specified location



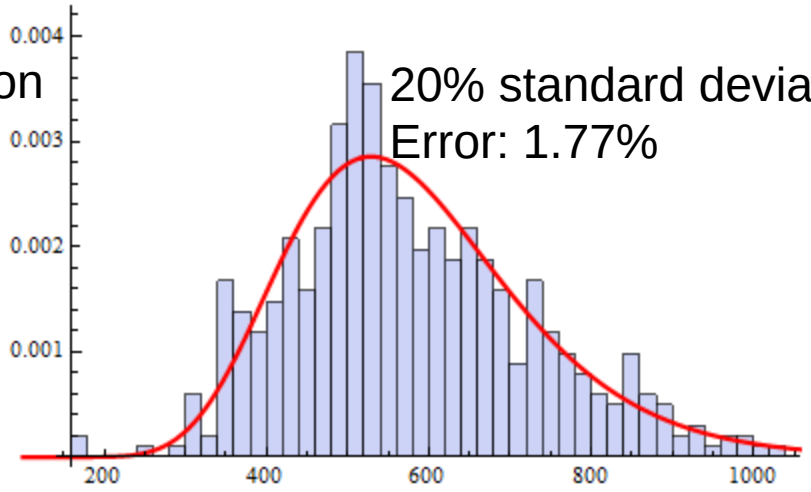
5% standard deviation
Error: 4.73%



10% standard deviation
Error: 6.48%



15% standard deviation
Error: 3.36%

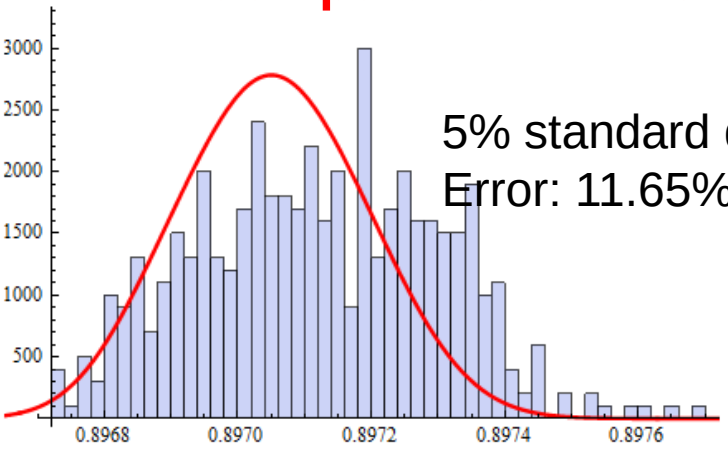


20% standard deviation
Error: 1.77%

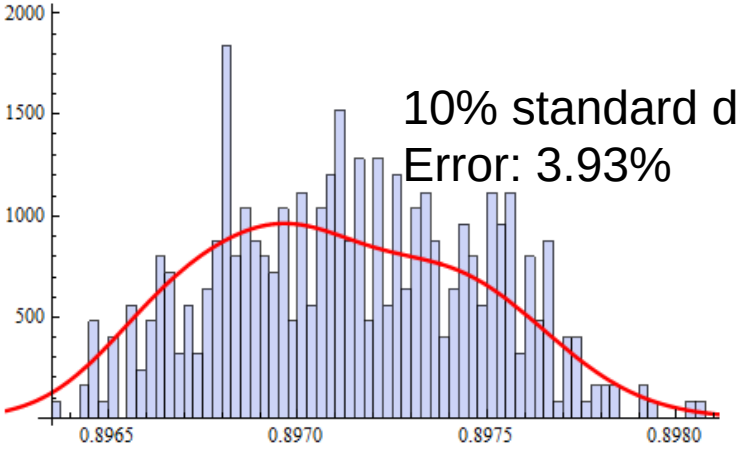
3dCfb MFIX scenario with 2X uniform

LHS computation time: 125.56 hours
QUICKER computation time: 36.16 hours
Computational time savings of 71.2%

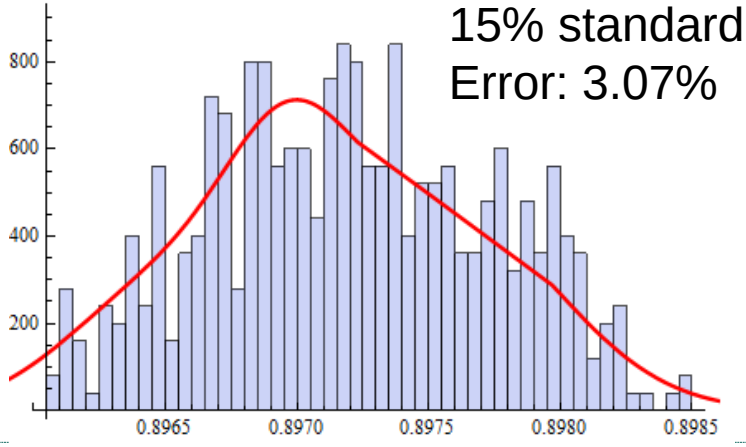
Measuring porosity at a specified location



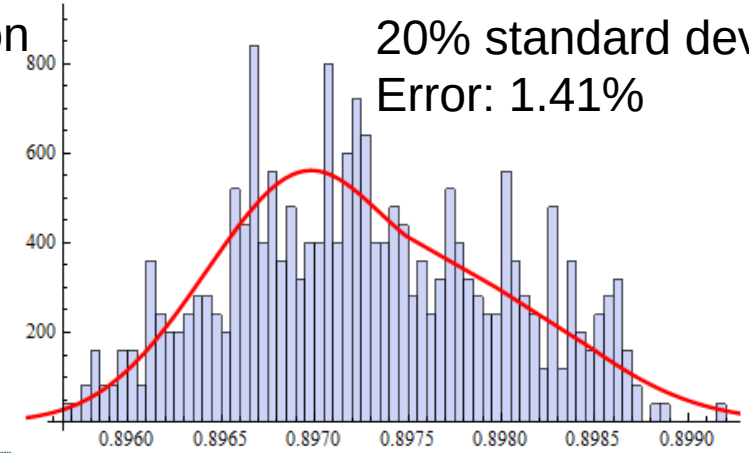
5% standard deviation
Error: 11.65%



10% standard deviation
Error: 3.93%



15% standard deviation
Error: 3.07%



20% standard deviation
Error: 1.41%

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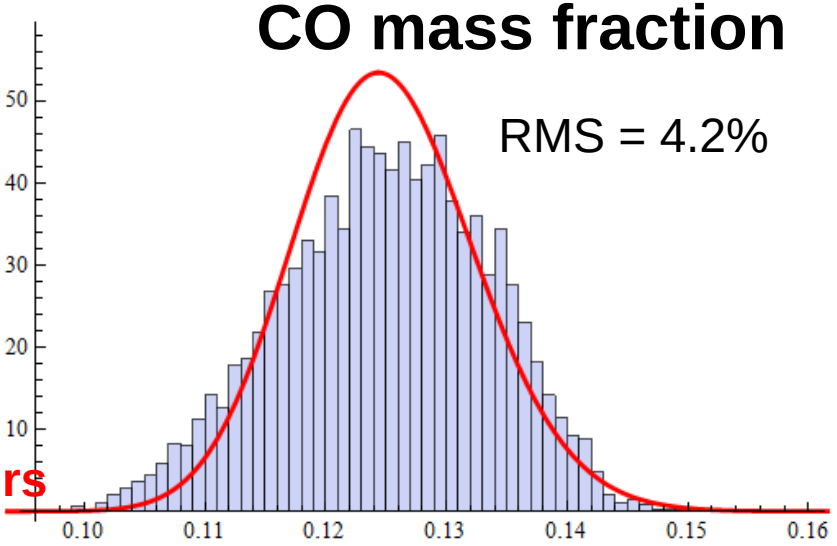
Results of a blind study

- Results of a blind chemical kinetics study
  - Using the QUICKER methodology, a set of samples points were provided to Dr. Aytekin Gel to run through his simulation
  - The developers of QUICKER had no prior knowledge of the specifics of this kinetics model

MC computation time: 1.52 hours
QUICKER computation time: 0.0019 hours
Computational time savings of 99.9%

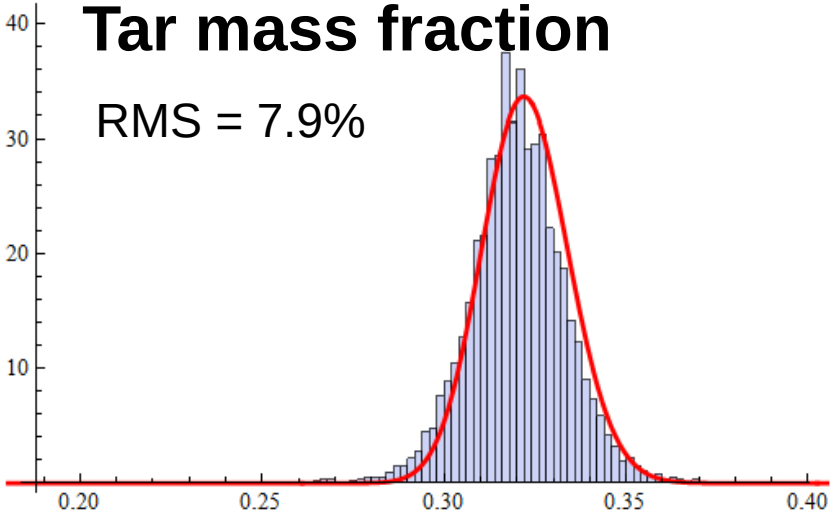
CO mass fraction

RMS = 4.2%



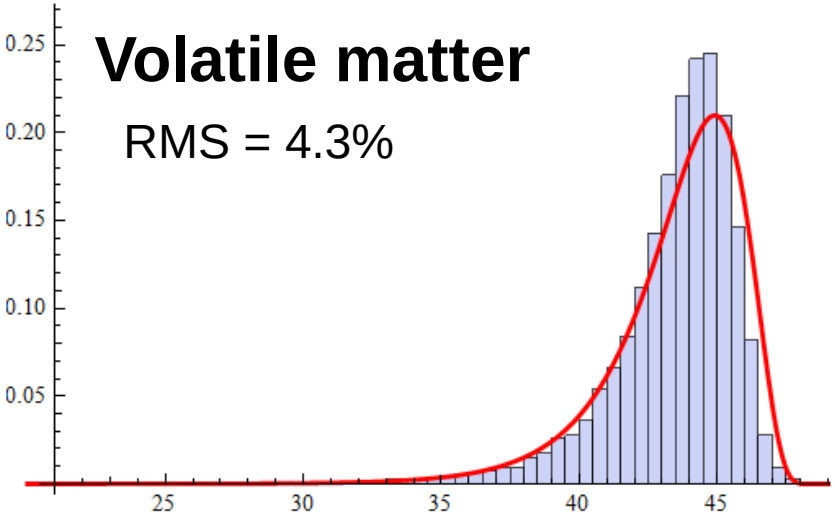
Tar mass fraction

RMS = 7.9%



Volatile matter

RMS = 4.3%



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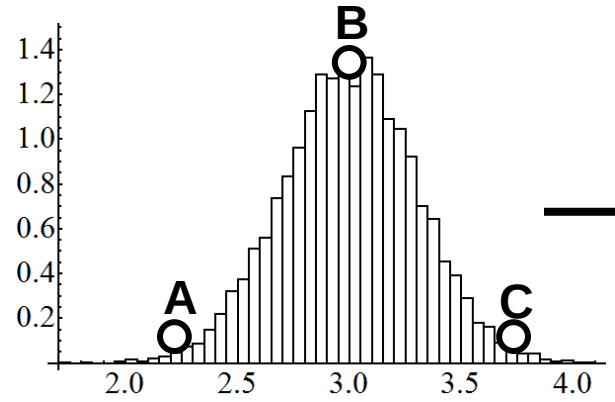
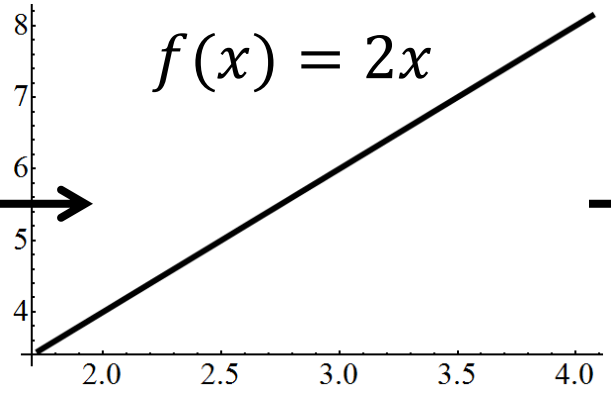
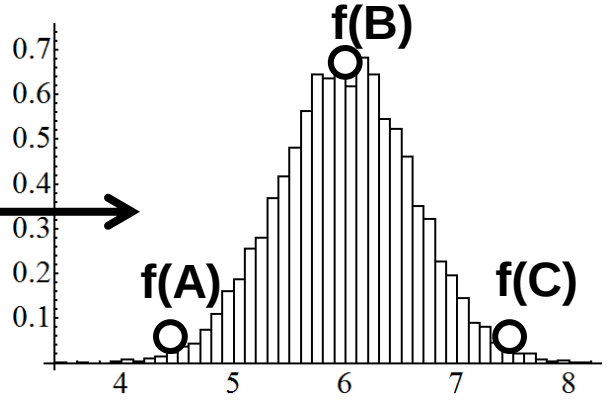
Gaussian input distribution



Monotonic system



Unimodal output distribution



Composite functions